# CERTAIN DYNAMIC AND STATIC CONTACT PROBLEMS OF THE THEORY OF elasticity for a circular cylinder of finite size* 

## M. I. CHEBAKOV

Axisymmetric, dynamic contact problems of the theory of elasticity concerning the vertical (problem 1) and torsional (problem 2) oscillations of a stamp lying on a plane boundary of a circular cylinder of finite size, are considered. In case of problem 1 it is assumed that the side surface of the cylinder is in contact with a smooth, rigid yoke, and for problem 2 the side surface of the cylinder is immovable. A static problem (problem 3) formulated analogously to problem 1 is also studied. The solutions of the above problems are obtained using the method of homogeneous solutions /l/. Conditions of generalized orthogonality of the axisymmetric homogeneous solutions are obtained for the problem of steady-state oscillations in a layer, in a manner analogous to that used in $/ 2 /$. A numerical example is solved, which shows that in a static problem with the cylinder height and radius of the stamp both fixed, the resistance of the cylinder against the penetration of the stamp is a nonmonotonous function of the cylinder radius. Problem 1 was solved by a different method in /3/, and a number of axisymmetric contact problems for a cylinder formulated in a similar manner were dealt with in /4-9/ et al.

1. Condition of generalized orthogonality in the problem of steady-state oscillations of a layer. Let us consider an elastic layer $|z| \leqslant h, r \geqslant 0(r, z, \varphi$ are cylindrical coordinates), and let the edges $z= \pm h$ of this layer be a) fixed, b) stressfree, or the edge $z=h$ be fixed and $z=-h$ stress-free. Seeking a solution of the Lamé equations in the form

$$
\begin{equation*}
u_{k}(r, \quad z)=A_{k}(z) J_{1}\left(p_{k} r\right), \quad w_{k}(r, \quad z)=B_{k}(z) J_{0}\left(p_{k} r\right) \tag{1.1}
\end{equation*}
$$

where $u_{k}(r, z) e^{i \omega t}$ and $w_{k}(r, z) e^{i \omega t}$ are the projections of the displacement vector on the $r$ and $z$-axis respectively, $\omega$ is the oscillation frequency and $t$ is time, we obtain the system of differential equations

$$
\begin{equation*}
A_{k}^{\prime \prime}+\left(\theta_{2}^{2}-\alpha p_{k}^{2}\right) A_{k}-(1-2 v)^{-1} p_{k} B_{k}^{\prime}=0, \alpha B_{k}^{\prime \prime}+\left(\theta_{2}^{2}-p_{k}^{2}\right) B_{k}+(1-2 v)^{-1} p_{k} A_{k}^{\prime}=0, \quad \theta_{2}^{2}=\frac{\mu \omega^{2}}{\mu} \tag{1.2}
\end{equation*}
$$

under the conditions that

$$
a=2 \frac{1-v}{1-2 v}
$$

a) $A_{k}( \pm h)=B_{k}( \pm h)=0$, b) $\sigma_{z k}^{*}( \pm h)=\tau_{k}^{*}( \pm h)=0$, c) $A_{k}(h)=B_{k}(h)=\sigma_{z k}^{*}(-h)=\tau_{k}^{*}(-h)=0$
where $\rho$ is density, $\mu$ and $v$ are the elastic constants of the material and the components of the stress tensor without the temporary multiplier have the form
$\sigma_{z k}(r, z)=\mu \sigma_{z k}^{*}(z) J_{0}\left(p_{k} r\right), \quad \tau_{r z k}(r, z)=\mu \tau_{k}^{*}(z) J_{1}\left(p_{k} r\right) ; \sigma_{\tau k}=\mu\left[\sigma_{r k}^{*}(z) J_{0}\left(p_{k} r\right)-2 A_{k}(z) r^{-1} J_{1}\left(p_{k} r\right)\right]$

$$
\begin{equation*}
\sigma_{z k}^{*}(z)=\beta p_{k} A_{k}(z)+\alpha B_{k}^{\prime}(z), \quad \tau_{k}^{*}(z)=A_{k}^{\prime}(z)-p_{k} B_{k}(z), \sigma_{r k}^{*}(z)=\alpha p_{k} A_{k}(z)+\beta B_{k}^{\prime}(z) \tag{1.4}
\end{equation*}
$$

Let the problem (1.2), (1.3) have simple eigenvalues only, and $p_{j}{ }^{2} \neq p_{n}{ }^{2}$. Then its eigenfunctions will satisfy the following relations of generalized orthogonality ( $\lambda$ is the elastic constant of the material):

$$
\begin{gather*}
U_{j n}=\int_{-h}^{h}\left[p_{j} p_{n} B_{j} B_{n}+0_{2}^{2} A_{j} A_{n}-A_{j}^{\prime} A_{n}^{\prime}\right] d z=0, \quad V_{j n}=\int_{-h}^{h}\left[p_{j} p_{n} A_{j} A_{n}+\theta_{1}^{2} B_{j} B_{n}-B_{j}^{\prime} B_{n}^{\prime}\right] d z=0  \tag{1.5}\\
W_{j n}=\int_{-h}^{h}\left[\sigma_{r j}^{*} A_{n}-B_{j} \tau_{n}^{*}\right] d z=0, \quad \theta_{1}^{2}=\frac{\rho \theta^{2}}{\lambda+2 \mu}
\end{gather*}
$$

The first two relations of (1.5) are obtained in a manner analogous to that used in $/ 2 /$ for a plane problem. It can also be shown that

[^0]\[

$$
\begin{equation*}
W_{j n}=2\left(p_{n}^{2}-p_{j}^{2}\right)^{-1}\left[p_{n} \sigma_{z n}^{*}(z) B_{j}(z)-p_{n} B_{n}(z) \sigma_{z j}^{*}(z)-p_{j} \tau_{j}^{*}(z) A_{n}(z)+p_{j} \boldsymbol{A}_{j}(z) \tau_{n}^{*}(z)\right] \mid h^{h} \tag{1.6}
\end{equation*}
$$

\]

from which the last relation of (1.5) follows with any form of the boundary condition (1.3) taken into account.
2. Vertical oscillations of a stamp. Let us consider an axisymmetric contact problem of vertical nonresonant oscillations of a stamp of radius a, lying without friction on a plane boundary of a circular cylinder of radius $R$ and height $h$, acted upon by a vertical force $p_{e^{-i \omega t}}$, under the following boundary conditions:

$$
\begin{align*}
& \sigma_{z}(r, z)=0 \quad(z=h, a<r<R), \quad w(r, z)=\delta(r) \quad(z=h, r \leqslant a)  \tag{2.1}\\
& \tau_{r z}(r, z)=0 \quad(z=h, \quad z=0, r \leqslant R), \quad w(r, \quad z)=0 \quad(z=0, r \leqslant R) \\
& \tau_{r z}(r, z)=u(r, z)=0 \quad(r=R, \quad 0 \leqslant z \leqslant h)
\end{align*}
$$

Here $u e^{-i \omega t}$, we $e^{-i \omega t}$ are the projections of the displacement vector on the $r$-and $z$-axis respectively, and $\sigma_{z} e^{-i \omega t}, \tau_{r z} e^{-i \omega t}$ are the components of the stress tensor. We solve the problem stated using the method of homogeneous solutions /1/. According to this method we first find a solution of the problem for the layer when

$$
\begin{gather*}
\sigma_{z}(r, z)=q(r) \quad(z=h, r \leqslant a), \quad \sigma_{z}(r, z)=0 \quad(z=h, r>a)  \tag{2.2}\\
\tau_{r z}(r, z)=0 \quad(z=h), \quad \tau_{r z}(r, z)=w(r, z)=0, \quad(z=0)
\end{gather*}
$$

Using the principle of limiting absorption /10/, we multiply the right-hand sides of the Lame equations by the corresponding weighing terms

$$
\varepsilon \rho \omega \partial\left(u e^{-i \omega t}\right) / \partial t, \quad \varepsilon \rho \omega \partial\left(\omega e^{-i \omega t}\right) / \partial t
$$

( $\varepsilon$ is the fictitious absorption coefficient) and seek a solution of such equations in the form $u e^{-i \omega t}$, we $e^{-i \omega t}$. Separating the variables and applying a Hankel transform to the resulting equations in $u$ and $w$, we obtain
$w^{(1)}(r, z)=\frac{1}{\mu} \int_{0}^{a} q(\rho) \rho d \rho \int_{0}^{\infty} L_{\varepsilon}(z, u) J_{0}(u r) J_{0}(u \rho) u d u, \quad u^{(1)}(r, z)=\frac{1}{\mu} \int_{0}^{a} q(\rho) \rho d \rho \int_{0}^{\infty} L_{1 e}(z, u) J_{1}(u r) J_{0}(u \rho) u d u$

$$
\begin{gathered}
r_{r=}^{(1)}(r, z)=\int_{0}^{a} q(\rho) \rho d \rho \int_{0}^{\infty} L_{2 \varepsilon}(z, u) J_{1}(u r) J_{0}(u \rho) u d u \\
L_{\varepsilon}(z, u)=B(z, u) \gamma(u), \quad L_{1 \varepsilon}(z, u)=A(z, u) \gamma(u) \\
L_{2 \varepsilon}(z, u)=\left[A^{\prime}(z, u)-u B(z, u)\right] \gamma(u), \quad \gamma(u)=\left[\beta u A(h, u)+\alpha B^{\prime}(h, u)\right]^{-1} \\
A(z, u)=u x_{\varepsilon}^{-1}\left[\left(\eta_{\varepsilon}^{2}+u^{2}\right) \operatorname{sh} \eta_{\varepsilon} h \operatorname{ch} x_{\varepsilon} z-2{\left.x_{\varepsilon} \eta_{\varepsilon} \operatorname{ch} \eta_{\varepsilon} z \operatorname{sh} x_{\varepsilon} h\right]}_{B(z, u)=-\left[\left(\eta_{\varepsilon}^{2}+u^{2}\right) \operatorname{sh} \eta_{\mathrm{e}} h \operatorname{sh} x_{\mathrm{E}} z-2 u^{2} \operatorname{sh} \eta_{\varepsilon} z \operatorname{sh} x_{\varepsilon} h\right]}\right. \\
x_{\varepsilon}^{2}=u^{2}-\rho \omega^{2}(1+i \varepsilon) /(\lambda+2 \mu), \quad \eta_{\varepsilon}^{2}=u^{2}-\rho \omega^{2}(1+i \varepsilon) / \mu
\end{gathered}
$$

where a prime denotes a derivative with respect to its first arqument.
In the second stage of the solution we construct a system of homogeneous solutions of the Lamé equations, transformed in the manner shown above, for a layer. We then have

$$
\sigma_{z}(r, z)=\tau_{r z}(r, z)=0 \quad(z=h), \quad w(r, z)=\tau_{r z}(r, z)=0, \quad(z=0)
$$

The above boundary conditions are equivalent to conditions $b$ ) given in sect.l, provided that the boundary value problem is continued symmetrically into the region $-h \leqslant z<0$. The projections of the displacement vector and the components of the stress tensor will have the form (1.1), (1.4), where

$$
\begin{equation*}
A_{k}(z)=A\left(z, p_{k}\right), \quad B_{k}(z)=B\left(z, p_{k}\right) \tag{2.4}
\end{equation*}
$$

and we must replace $\boldsymbol{x}_{\varepsilon}{ }^{2}$ and $\eta_{\varepsilon}{ }^{2}$ by

$$
x_{k \varepsilon}^{2}=p_{k}^{2}-\rho \omega^{2}(1+i \varepsilon) /(\lambda+2 \mu), \quad \eta_{k \varepsilon}^{2}=p_{k}^{2}-\rho \omega^{2}(1+i \varepsilon) / \mu, \quad\left(\beta p_{k} A_{k}(h)+\alpha B_{k}^{\prime}(h)=0\right)
$$

respectively, whexe $p_{k}$ are the roots of the equation contained within the brackets.
In the third stage we introduce the functions
$u^{(2)}(r, z)=\sum_{k=1}^{\infty} D_{k} A_{k}(z) J_{1}\left(p_{k} r\right), \quad w^{(2)}(r, z)=\sum_{k=1}^{\infty} D_{k} B_{k}(z) J_{0}\left(p_{k} r\right), \quad \tau_{r z}^{(2)}(r, z)=\sum_{k=1}^{\infty} D_{k} \tau_{k}^{*}(z) J_{1}\left(p_{k} r\right)$
where the summation is carried out over all $p_{k}$ for which $\operatorname{Im}\left(p_{k}\right)>0$, and $D_{k}$ are unknown coefficients. Then we can write the solution of the problem formulated at this stage in the form

$$
\begin{equation*}
u(r, z)=u^{(1)}(r, z)-u^{(2)}(r, z), \quad w(r, z)=w^{(1)}(r, z)-w^{(2)}(r, z) \tag{2,6}
\end{equation*}
$$

We find the coefficients $D_{k}$ of the expansion (2.5) from the condition

$$
u(r, z)=0, \tau_{r z}(r, z)=\tau_{r z}^{(1)}(r, z)-\tau_{r z}^{(2)}(r, z)=0 \quad(r=R)
$$

which we shall rewrite thus

$$
\sum_{k=1}^{\infty} D_{k} A_{k}(z) J_{1}\left(p_{k} R\right)=u^{(1)}(R, z), \quad \sum_{k=1}^{\infty} D_{k} \tau_{k}^{*}(r) J_{1}\left(p_{k} R\right)=\mu^{-1} \tau_{r z}^{(1)}(R, z)
$$

Let us multiply the first equation of the above relations by $\sigma_{r j}{ }^{*}(z)$, the second by $B_{j}(z)$, subtract the second from the first and integrate from - $h$ to $h$. Taking into account the last relation of (1.5) which holds also when $\varepsilon \neq 0$, we obtain

$$
\begin{align*}
& D_{k}=\left(\mu W_{k k} J_{1}\left(p_{k} R\right)\right)^{-1} \int_{-h}^{n}\left[\mu u^{(1)}(R, z) \sigma_{r k}^{*}(z)-\tau_{r z}^{(1)}(R, z) B_{k}(z)\right] d z=\left(\mu W_{k k} J_{1}\left(p_{k} R\right)\right)^{-1} \int_{0}^{a} q(\rho) \Omega_{k}(\rho) \rho d \rho  \tag{2.7}\\
& \Omega_{k}(\rho)=\int_{0}^{\infty} M_{k}(u) J_{1}(u R) J_{0}(u \rho) u d u, \quad M_{k}(u)=\gamma(u) \int_{-h}^{h}\left[A(z, u) \sigma_{r k}^{*}(z)-\left(A^{\prime}(z, u)-u B(z, u)\right) B_{k}(z)\right] d z
\end{align*}
$$

Equating the last relations of (2.7) and (1.5) we obtain $M_{k}\left(p_{j}\right)=\gamma\left(p_{j}\right) W_{k j}$, where the function $\gamma(u)$ is given by (2.3). Taking into account the boundary conditions for the homogeneous solutions and the relation (1.6) for $W_{k j}$, we obtain
$M_{k}(u)=2 u B_{k}(h)\left(u^{2}-p_{k}^{2}\right)^{-1}, \quad \Omega_{k}(\rho)=2 B_{k}(h) \int_{0}^{\infty} \frac{u^{2}}{u^{2}-p_{k}^{2}} J_{1}(u R) J_{0}(u \rho) d u=-2 B_{k}(h) i p_{k} I_{0}\left(-i \rho p_{k}\right) K_{1}\left(-i R p_{k}\right)$
The last integral is taken from /11/, taking into account the fact that $\operatorname{Im}\left(p_{k}\right) \neq 0$ for all $p_{k}: I_{0}(x)$ and $K_{1}(x)$ are modified Bessel functions.

We find now that all conditions (2.1) of the problem 1 hold, with exception of the condition

$$
w(r, z)=w^{(1)}(r, z)-w^{(2)}(r, z)=\delta(r) \quad(z=h, r \leqslant a)
$$

Let us introduce the operator $K_{r h^{\varepsilon}} q=\mu w^{(\mathbf{1})}(r, h)$, where $w^{(\mathbf{1})}(r, h)$ is defined by one of the formulas of (2.3). Then, satisfying the last condition, we obtain the following integral equation for the contact pressure $q(\rho)$ under the stamp:

$$
\mu^{-1} K_{r h}^{\varepsilon} q=\delta(r)+\sum_{k=1}^{\infty} D_{k} B_{k}(h) J_{0}\left(p_{k} r\right) \quad(r \leqslant a)
$$

Writing now $q(\rho)$ in the form

$$
\begin{equation*}
q(\rho)=\frac{\mu}{1-v}\left[q_{0}(\rho)+\sum_{k=1}^{\infty} D_{k} B_{k}(h) q_{k}(\rho)\right] \tag{2.8}
\end{equation*}
$$

where $q_{k}(\rho)$ is the solution of the integral equations

$$
\begin{equation*}
K_{r h^{\varepsilon}} q_{0}=(1-v) \delta(r) \quad(r \leqslant a), \quad K_{r h}^{\varepsilon} q_{k}=(1-v) J_{0}\left(p_{k} r\right), \quad(k \geqslant 1, \quad r \leqslant a) \tag{2.9}
\end{equation*}
$$

and substituting (2.8) into (2.7), we obtain an infinite system of linear algebraic equations for determining the constants $D_{k}$ of the expansion (2.8):

$$
\begin{gather*}
x_{k}=g_{k}+\sum_{n=1}^{\infty} a_{l \cdot n} x_{n}\left(x_{k}=D_{k} B_{k}(h) I_{1}\left(R \gamma_{k} / h\right), k \geqslant 1\right), a_{k n}=-2 i \gamma_{k} W_{k \cdot k}^{-1} B_{k}^{2}(h) K_{\mathbf{1}}\left(R \gamma_{k} / h\right) I_{1}^{-1}\left(R \gamma_{n} / h\right) T_{n, k}  \tag{2.10}\\
g_{k}=-2 i \gamma_{k} W_{k h}^{-1} B_{k}^{2}(h) K_{1}\left(R \gamma_{k} / h\right) T_{0, k}, \quad \gamma_{k}=-i p_{k} h, \quad T_{n, k}=\int_{0}^{\infty} q_{n}(\rho) I_{0}\left(\rho \gamma_{k} / h\right) \rho d \rho
\end{gather*}
$$

Until now we assumed that the coefficient of fictitious absorption of the medium $\varepsilon>0$. Making e tend to zero, we obtain a solution of the initial problem l. It must be remombered here /12/ that some of the zeros and poles of the function $L_{e}(h, u)$ given in (2.3) will pass, as $\varepsilon \rightarrow 0$, to the real axis, and this will distort the contour of integration in the expression for the kernel of the integral equations (2.9). The authors of $/ 12 /$ discuss the shape of such a contour $\Gamma$ in detail.

If follows that the contact pressure is defined by the formula

$$
\begin{equation*}
q(\rho)=\frac{\mu}{t-v}\left[q_{0}(\rho)+\sum_{k=1}^{\infty} x_{k} I_{1}^{-1}\left(\gamma_{k} R / h\right) q_{k}(\rho)\right] \tag{2.11}
\end{equation*}
$$

where $x_{k}$ is a solution of the system (2.1) for $\varepsilon=0, q_{k}(\rho)$ is a solution of the known /12/ integral equations $\left(q_{k}(a \rho)=\vartheta_{k}(\rho)\right)$ written in dimensionless variables

$$
\begin{gather*}
\int_{0}^{1} v_{k}(\rho) \rho d \rho \int_{\Gamma} L(u \lambda) J_{0}(u r) J_{0}(u \rho) d u=f_{k}(r) \quad(r \leqslant 1)  \tag{2.12}\\
L(\tau)=\frac{\theta_{2}^{* z}(1-v)^{-1} \tau 火 \operatorname{sh} \times \operatorname{ch} \eta}{4 \tau^{2} \kappa \eta \operatorname{ch} \eta \operatorname{sh} x-\left(\eta^{2}+\tau^{2}\right)^{2} \operatorname{sh} \eta \operatorname{ch} x}, \quad \lambda=\frac{h}{a}, x^{2}=\tau^{2}-\theta_{1}^{* 2}, \eta^{2}=\tau^{2}-\theta_{2}^{* 2}, \quad \theta_{1}^{* 2}=\frac{\rho \omega^{2} h}{\lambda+2 \mu}, \theta_{2}^{* 2}=\frac{\rho \omega^{2} h}{\mu}  \tag{2.13}\\
f_{k}(r)=\left\{\delta(r a), \quad \text { if } \quad k=0 ; \quad I_{0}\left(a \gamma_{k} r / h h\right) \quad \text { if } \quad k \geqslant 1\right\} \tag{2.14}
\end{gather*}
$$

Moreover we shall assume in (2.12) that $\gamma_{k}$ are poles of the function $L(\tau)(2.13)$. The contour $\Gamma$ coincides with the positive part of the real axis everywhere except on the segments containing real poles of the function $L(\tau) / 12 /$. In the case of alternating the zeros and poles of this function, the segments indicated are bypassed by the contour from below $/ 12 /$.

Let us investigate the infinite system (2.10). We know $/ 12 /$ that the function $L(\tau)$ has a finite number of real zeros and poles and that the number increases with increasing reduced frequency $\quad \theta_{2}{ }^{*}$. At large numerical values the complex poles of the function $L(\tau)$ have the following asymptotic representation (*) $\left(a_{i}(i=1,2,3,4)\right.$ are real constants)

$$
\begin{equation*}
z_{n}=i h \gamma_{n} \sim i n a_{1}+a_{2} \ln \left(a_{3} n+a_{4}\right) \tag{2.15}
\end{equation*}
$$

Taking into account (2.15) we can show as was done in $/ 1,13 /$, that at large numerical values the coefficients of the infinite system (2.10) have the following asymptotics $(k, n \rightarrow \infty)$ :

$$
\begin{equation*}
\left|g_{k}\right| \sim k^{-1} \exp \left[-a_{1} k(R-a) / h\right], \quad\left|a_{k n}\right| \sim k^{-1} \exp \left[-a_{1}(k+n)(R-a) / h\right] \tag{2.16}
\end{equation*}
$$

It follows therefore that the system (2.10) belongs to the class of the normal Poincaré-Koch systems and can be solved by the reduction method for any value of the parameter $(R-a) / h>0$.
3. Torsional oscillations of a stamp. We shall consider an axisymmetric contact problem of nonresonant torsional oscillations of a stamp of radius $a$, rigidly coupled to the plane boundary of a circular cylinder of radius $R$ and height $h$, acted upon by the moment $M e^{-i \omega t}$, with the following boundary conditions:

$$
\begin{align*}
& v(r, z)=\delta r(r \leqslant a, z=h), \quad \tau_{z \varphi}(r, z)=0 \quad(a<r<R, z=h)  \tag{3.1}\\
& v(r, z)=0 \quad(z=0, r \leqslant R \quad \text { and } \quad r=R, \quad 0 \leqslant z \leqslant h)
\end{align*}
$$

Here $v e^{-i \omega t}$ denotes the displacement along the $\varphi$-axis, $\tau_{z \varphi} e^{-i \omega t}$ are the tangential stresses and $\delta$ is the stamp oscillation amplitude.

Using the method of homogeneous solutions which was used to solve an analogous static problem in $/ 13 /$, we reduce the present problem to that of investigating the infinite system (2.10) with the coefficients

$$
\begin{equation*}
g_{k}=2(-1)^{k} K_{1}\left(R \gamma_{k} / h\right) T_{0, k}, \quad a_{k n}=2(-1)^{k+n} h^{-1} K_{1}\left(R \gamma_{k} / h\right) I_{1}^{-1}\left(R \gamma_{1} / h\right] T_{n, k} \tag{3.2}
\end{equation*}
$$

$$
\begin{aligned}
T_{n, k}=\int_{0}^{a} \tau_{n}(\rho) I_{1}\left(\rho \gamma_{k} / h\right) \rho d \rho, \quad i \gamma_{k} & =\left[x^{2}-\pi^{2}(k-1 / 2)^{2}\right]^{1 / 2}, L(u)-\left(\sqrt{u^{2}-x^{2}}\right)^{-1} u \text { th } \sqrt{u^{2}-x^{2}}, \quad x^{2}=\rho \omega^{2} h^{2} \mu^{-1} \\
f_{k}(x) & =\left\{\delta x \quad \text { if } k=0 ; a^{-1} I_{1}\left(a \gamma_{k} x / h\right) \text { if } k \geqslant 1\right\}
\end{aligned}
$$

Here $\tau_{n}(a \rho)=\boldsymbol{\vartheta}_{n}(\rho)$ are solutions of the integral equations (2.12) for $n=1, z_{k}=i \gamma_{k}$ are the poles of the function $L(u)$, and the contour was chosen according to Sect.2. The tangential contact stresses under the stamp are defined by the formula

$$
\begin{equation*}
\tau(r)=\mu \tau_{0}(r)+\frac{\mu}{h} \sum_{k=1}^{\infty} x_{k}(-1)^{k} \tau_{k}(r) I_{1}^{-1}\left(R \gamma_{k} / h\right) \tag{3.3}
\end{equation*}
$$

The asymptotic expressions (2.16) where $a_{1}=\pi$ hold also for the coefficients of (3.2), therefore the system (2.10) with the coefficients (3.2) helongs to the normal Poincare - Koch systems.
4. Static contact problem. Consider an axisymmetric static contact problem of imbedding a stamp of radius $a$ into a plane boundary of a circular cylinder of radius $R$ and height $h$, using a force $p$. The boundary conditions have the form (2.1) where $u$ and $w$ are projections of the displacement vector, and $\sigma_{z}, \tau_{r z}$ are components of the stress tensor. Again, as in Problem 1, we use the method of homogeneous solutions to find the contact pressure according to the formula (2.11) in which $x_{k}$ is the solution of a system of the form (2.10) with the coefficients given by

[^1]\[

$$
\begin{gather*}
g_{k}=\operatorname{tg}^{2} \gamma_{k} K_{1}\left(R \gamma_{k} / h\right) T_{0, k}, \quad a_{k n}=h^{-1} \operatorname{tg}^{2} \gamma_{k} K_{1}\left(R \gamma_{k} / h\right) I_{1}^{-1}\left(R \gamma_{k} / h\right) T_{n, k}  \tag{4.1}\\
L(u)=(\operatorname{ch} 2 u-1)(2 u+\operatorname{sh} 2 u)^{-1} \tag{4.2}
\end{gather*}
$$
\]

The function $T_{n, k}$ is given in (2.10), $q_{k}(a \rho)$ represents a solution of the integral equation (2.12) in which $f_{k}(r)$ has the form (2.14) and $i \gamma_{k}$ are complex poles of the function $L(\tau)$ lying in the upper half-plane. Since the function $L(\tau)$ has no real poles, it follows that the contour $\Gamma$ in (2.12) will fully coincide with the positive part of the real axis. The infinite system (2.10)- (4.1) will, in this case, also belong to the normal Poincare-Koch systems.
5. Solution of the integral equations (2.12). Contact problems for an elastic layer analogous to the Problems $1-3$, can be reduced to integral equations of the type (2.12). Such equations have been exhaustively studied, and their solutions can be obtained using e.g. asymptotic methods $/ 14 /$. We know (see e.g. /15/) that, when $\lim L(\tau)=1+O\left(\tau^{-2}\right)(\tau \rightarrow 0)$ the equation (2.12) is equivalent to the inteqral equation of the second kind

$$
\begin{gather*}
\varphi_{k}(t)=\frac{1}{\pi \lambda} \int_{-1}^{1} \varphi_{k}(\tau) M\left(\frac{t-\tau}{\lambda}\right) d \tau+d_{k}(t) \quad(|t| \leqslant 1)  \tag{5.1}\\
M(y)=\int_{\Gamma}[1-L(u)] \cos u y d u \tag{5.2}
\end{gather*}
$$

where $L(u)$ is (2.13) (Problem 1), (3.3) (Problem 2) or (4.2) (Problem 3). In the case of dynamic problems the contour $\Gamma$ is situated as in Sects. 2 and 3, and for the static problem it coincides with the positive part of real axis. Moreover, for Problems 1 and 3 we have

$$
\begin{equation*}
\vartheta_{k}(r)=-\frac{2}{\pi} \frac{d}{d r} r \int_{r}^{1} \frac{\varphi_{k}(\tau) d \tau}{\tau \sqrt{\tau^{2}-r^{2}}}, \quad d_{k}(t)=\frac{d}{d t} \int_{0}^{t} \frac{r f_{k}(r) d r}{\sqrt{t^{2}-r^{2}}} \tag{5.3}
\end{equation*}
$$

and for Problem 2 we have

$$
\begin{equation*}
\mathfrak{\vartheta}_{k}(r)=-\frac{2}{\pi} \frac{d}{d r} \int_{r}^{1} \frac{\varphi_{k}(t) d t}{\sqrt{t^{2}-r^{2}}}, \quad d_{k}(t)=\frac{d}{d t} t \int_{0}^{t} \frac{f_{k}(r) d r}{\sqrt{t^{2}-r^{2}}} \tag{5.4}
\end{equation*}
$$

We use the method of large $\lambda$ (see e.g. /16/) to solve the integral equation (5.1), (5.2). To do this, we must write the kernel (5.2) in the form of an expansion in positive powers of
$|y|$. This is easily done for Problem $3 / 14 /$

$$
\begin{equation*}
M(y)=\sum_{k=0}^{\infty} b_{k} y^{2 k}, \quad b_{k}=\frac{(-1)^{k}}{(2 k)!} \int_{0}^{\infty}[1-L(u)] u^{2 k} d u \tag{5.5}
\end{equation*}
$$

and in this case we can write the solution of the equation (5.1), (5.5) for large $\lambda$ in the form /13,16/

$$
\begin{equation*}
\varphi_{m}(t)=d_{m}(t)+\sum_{j=0}^{M} H_{j}{ }^{\prime \prime \prime} t^{2 j}, \quad H_{j}^{\prime \prime \prime}(\lambda)=\sum_{s=j}^{M} \lambda^{-(\underline{s}+1)}\left[\beta_{s i}^{m 2}+\lambda^{-1} d_{s+1, j}^{m}\right] \tag{5.6}
\end{equation*}
$$

where $M$ is an arbitrarily large number and the coefficients $\beta_{s j^{m}}$ and $\alpha_{s j}{ }^{m \prime \prime}$ are found from the simple recurrence relations

$$
\begin{align*}
& \alpha_{s j}{ }^{m}=\frac{2}{\pi} \sum_{k=j}^{s-1} b_{k} z_{k j} \sum_{p=0}^{s-k-1} \frac{\beta_{s-k-1, p}^{m}}{2 p+2 k-2 l+1} \quad\binom{s=1}{0 \leqslant i \leqslant s-1}  \tag{5.7}\\
& \beta_{s j}^{\prime \prime \prime}=\frac{2}{\pi}\left[a^{-1} b_{s} z_{s j} F_{s-j}^{m}+\sum_{k=j}^{s-1} b_{k} z_{k j} \times \sum_{p=0}^{s-k-1} \frac{a_{s=k}^{m \prime \prime}, p}{2 p+2 k-2 l-1}\right] \quad\binom{s \geqslant 0}{0 \leqslant j \leqslant s} \\
& \beta_{00}{ }^{m}=\frac{2}{\pi} b_{0} z_{00} a^{-1} F_{0}{ }^{m}, z_{k} ;=(2 h)![(2 j)!(2 k-2 j)!]^{-1} \\
& F_{k}{ }^{0}=\delta(2 k+1)^{-1} . \quad F_{k}^{\prime \prime 2}=\frac{(2 k)!}{\left(a \gamma_{m}\right)^{2 k+1}}\left[\sum_{i=0}^{k} \frac{\left(a \gamma_{m}\right)^{2 i}}{(2 i)!} \operatorname{sh} a \gamma_{m}-\sum_{i=1}^{k} \frac{\left(\left(i \gamma_{m}\right)^{2 i-1}\right.}{(2 i-1)!} \operatorname{ch} a \gamma_{m}\right] \quad(m \geqslant 1) \tag{5.8}
\end{align*}
$$

Thus in the case of large values of the parameter $\lambda\left(\lambda_{0}<\lambda<\infty\right)$ we can solve (5.6) with any degree of accuracy.

For the kernel (5.2) of Problems 1 and 2 the following expansion holds:

$$
\begin{equation*}
M(y)=\sum_{k=0}^{\infty} b_{k}|y|^{k} \quad\left(0 \leqslant y \leqslant y_{0}<\infty\right) \tag{5.9}
\end{equation*}
$$

We shall show how this expansion can be obtained for Problem 2, since for Problem 1 the procedure will be exactly the same. Let us write $L(u)$ in the form $L(u)==L_{1}(u)+L_{2}(u)$ under the condition

$$
\begin{equation*}
L_{2}(u)=o\left(e^{-2 u}\right), \quad L_{1}(u)=1-\sum_{i=1}^{\infty} c_{i} u^{-2 i} \quad(u \rightarrow \infty) \tag{5.10}
\end{equation*}
$$

This can be done if

$$
\begin{equation*}
L_{1}(u)=\frac{u}{\sqrt{u^{2}-x^{2}}}, \quad L_{2}(u)=\frac{u\left(\operatorname{th} \sqrt{u^{2}-x^{2}}-1\right)}{\sqrt{u^{2}-x^{2}}} \tag{5.11}
\end{equation*}
$$

Then we have

$$
\begin{gathered}
M(y)=M_{1}(y)+M_{2}(y), \quad M_{\mathbf{2}}(y)=\int_{\Gamma} L_{2}(u) \cos u y d u=\sum_{k=0}^{\infty} y^{2 k}(-1)^{k}[(2 k)!]^{-1} \int_{\Gamma} L_{2}(u) u^{2 k} d u \\
M_{1}(y)=\int_{\Gamma}\left[1-L_{1}(u)\right] \cos u y d u=\sum_{k=0}^{\infty} b_{k}^{*}|y|^{k}, \quad b_{2 k+1}^{*}=\frac{\pi(-1)^{k} c_{k+1}}{2(2 k+1)!}, \quad b_{2 k}^{*}=\frac{(-1)^{k}}{(2 k)!} \int_{\Gamma}\left[1-L(u)-\sum_{i=1}^{k} \frac{c_{i}}{u^{2 i}}\right] u^{2 k} d u
\end{gathered}
$$

$M_{1}(y)$ can be expanded into a series in the same manner as (1.3) in /17/. Thus the kernel (5.2) of the integral equation (5.1) can be written for Problems 1 and 2 in the form of a series (5.9), and solved using the method of large $\lambda$, with any degree of accuracy, in the form (5.6) where

$$
\begin{equation*}
H_{j}^{m}\left(\lambda_{i}\right)=\sum_{j=1}^{M} \lambda^{-3 s}\left[\eta_{2 s, j}^{m}+\lambda^{-1} \eta_{2 s+1, j}^{m} \mid\right. \tag{5.12}
\end{equation*}
$$

and the coefficients $\eta_{s j}^{m}$ are given by recurrent relations of the type (1.6) of $/ 16 /$.
Knowing the solution of (5.1) in the form (5.6), and using the expressions (5.3) and (5.4), we can now obtain simple expressions for calculating the coefficients of the system (2.10) for Problems 1 and 2.
6. Example. We shall consider a static problem of imbedding a flat stamp ( $\delta(r)=\delta=$ const) into an elastic cylinder (Problem 3, Sect.4). We have the following contact stresses for this problem:
$q(r)=\frac{\mu \delta}{1-v}\left[q_{0}(r)+\frac{1}{h} \sum_{k=1}^{\infty} x_{k} I_{1}^{-1}\left(\gamma_{k} R / h\right) q_{k}(r)\right] \quad(r \leqslant a), \quad q_{k}(\rho a)=\frac{2}{\pi}\left[\sum_{j=0}^{M} H_{j}^{k}(\lambda) S_{j}(\rho)+G_{k}(\rho)\right] \quad(\rho \leqslant 1, M \rightarrow \infty)$

$$
C_{0}(\rho)=n^{-1} S_{0}(\rho), \quad C_{\hbar}(\rho)=n^{-1} \frac{d}{d \rho} \rho \int_{D}^{1} \operatorname{ch}\left(u \gamma_{m} t / h\right) t^{-1}\left(t^{2}-\rho^{2}\right)^{-1 / 2} d t \quad(k \geq 1)
$$

$$
S_{j}(\rho)=\frac{1}{\sqrt{1-\rho^{2}}} \sum_{k=0}^{j-1} \frac{(i-1)!\left(2 j \rho^{2}-2 j+2 k+1\right)}{k!(j-k-1)!(2 k+1)}\left(1-\rho^{2}\right)^{k} \rho^{2(j-k-1)}
$$

The relation connecting the force $p$ acting on the stamp with the displacement $\delta$ of the stamp is given by the formulas
$P=\frac{4 a^{2} \mu \delta}{1-v}\left[P_{0}+\frac{1}{h} \sum_{k=1}^{\infty} x_{k} I_{1}^{-1}\left(\gamma_{k} R / h\right) P_{k}\right], \quad P_{k}=R_{k}+\sum_{j=0}^{M} H_{j}^{k}(\lambda)(2 j+1)^{-1}, \quad R_{0}=\delta a^{-1} R_{k}=h a^{-2} i_{k}^{-1} \operatorname{sh}\left(a \gamma_{k}\left(H_{i}\right) \quad(l \geqslant 1)\right.$
where $x_{k}$ is the solution of the infinite system (2.10) with coefficients (4.1), where
$T_{n, k}=\frac{2 a^{2}}{\pi}\left[\sum_{j=0}^{M} H_{j}^{n}(\lambda) F_{j}{ }^{k}+t_{n, k}\right] \quad(M \rightarrow \infty), \quad t_{0, k}=a^{-2} h_{h}^{-1} \operatorname{sh} \frac{a \gamma_{k}}{h}, \quad t_{n, k}=\frac{h \operatorname{sh}\left[a\left(\gamma_{n}+\gamma_{h}\right) / h\right]}{2 a^{2}\left(\gamma_{n}+\gamma_{k}\right)}+\frac{h \operatorname{sh}\left[a\left(\gamma_{n}-\gamma_{k}\right) / h\right]}{2 a^{2}\left(\gamma_{n}-\gamma_{h}\right)}$
The quantities $F_{j}^{k}$ are given by the formulas (5.8), $H_{j}{ }^{i}(\lambda)$ by (5.6) and (5.7), and $\gamma_{i,}$ denote the zeros of the function $2 u+\sin 2 u$ lying in the right half-plane ( $\gamma_{m} \neq 0$ ). Their asymptotic behavior at large values of $m$ is known and given by /14/

$$
\gamma_{m} \sim \pi(m-1 / 4) \pm d / 2 \ln (4 \pi m-\pi) \quad(m \rightarrow \cdots)
$$

A Fortran program was written for numerical solution using the computer BESM-6. The dimensionless quantities

$$
\begin{equation*}
P^{*}=P(1-v)(\mu \delta)^{-1}: \quad q^{*}(\rho)=q(\rho a)(1-v) d(\mu \delta)^{1} \quad(\rho \leqslant 1) \tag{6.4}
\end{equation*}
$$

were studied for various values of the parameter $\lambda$ and $R^{*} \quad R / a$. The values of $P$ and $q(r)$ were found from (6.2) and (6.1), respectively. The proposed algorithm yields the values of

$P^{*}$ and $q^{*}(\rho)$ for $\lambda \geqslant 1$ with practically any degree of accuracy, and the solution of the infinite system of linear algebraic equations is obtained using the reduction method. The quantity $M$ of (5.6) was assumed finite in (6.1)-(6.3), and this enabled us to obtain $p^{*}$ and $q^{*}(\rho)$ with an accuracy of up to the terms of the order of $\lambda-2 M-1$. We note that the larger the parameter $(R-a) /$
$h$, the fewer equations of the reduced infinite system are required (see /13/ for a more detailed discussion of convergence of the proposed algorithm). Below we give the values of the quantities $P^{*}$ and $q^{*}(\rho)$ for various $\lambda$, $R^{*}$ and $\rho$ :

|  | $\lambda=2$ |  |  |  |  |  |  |  |  |  |
| :--- | :--- | :--- | :--- | :---: | :--- | :--- | :--- | :--- | :---: | :---: |
| $R^{*}$ | 1.5 | 2.0 | 2.2 | 2.4 | 2.6 | 2.8 | 3.0 | $\infty$ |  |  |
| $P^{*}$ | 5.126 | 6.096 | 6.142 | 6.143 | 6.126 | 6.103 | 6.082 | 6.024 |  |  |
| $q^{*}(0.20)$ | 0.971 | 1.022 | 1.029 | 1.032 | 1.034 | 1.035 | 1.036 | 1.039 |  |  |
| $q^{*}(0.95)$ | 2.509 | 2.995 | 3.053 | 3.053 | 3.051 | 3.043 | 3.033 | 3.002 |  |  |
|  |  |  | $\lambda=4$ |  |  |  |  |  |  |  |
| $R^{*}$ | 1.5 | 2.0 | 2.5 | 3.0 | 3.8 | $\infty$ |  |  |  |  |
| $P^{*}$ | 2.948 | 4.075 | 4.616 | 4.844 | 4.940 | 4.882 |  |  |  |  |
| $q^{*}(0.20)$ | 0.460 | 0.612 | 0.702 | 0.750 | - | 0.801 |  |  |  |  |
| $q^{*}(0.95)$ | 1.351 | 2.001 | 2.311 | 2.444 | - | 2.480 |  |  |  |  |

Analysing the numerical values of $P^{*}$ for fixed $\lambda$ we can conclude that, when the parameter $R^{*}$ increases from zero to some value depending on $\lambda$, the resistance of the cylinder against the imbedding of the stamp also increases. When the value of $R^{*}$ is increased further, the resistance diminishes and tends to some constant value. This is illustrated in the Fig.l where $P^{*}$ is plotted against $R^{*}$ for $\lambda=2$. We note that the proposed algorithm yields solutions of the dynamic Problems 1 and 2 with any degree of accuracy also when $\lambda>\lambda^{*}(\omega)$, and in this case $\lambda^{*}(\omega)$ increases with the increasing frequency $\omega$.

The author thanks V. M. Aleksandrov for attention given and for assessing the results.
REFERENCES

1. ALEKSANDROV V.M., Method for homogeneous solutions in contact problems of the theory of elasticity for bodies of finite size. Izv. Sev. - Kavkazsk. nauchn. tsentra vysshei shkoly. Ser. estestv. nauk, No.4, 1974.
2. ZILBERGLET A.S. and NULLER B.M., Generalized orthogonality of homogeneous solutions in dynamic problems of the theory of elasticity. Dokl. Akad. Nauk SSSR, Vol. 234, No. $2,1977$.
3. BELOKON' A.V. and VATUL'IAN T.I., Dynanic contact problem for a finite cylinder. In coll. Tezisy dokl. Vses. nauchno-tekhn. konf. "Zhestkost' mashinostroitel'nykh konstruktsii", Briansk 1976, Moscow 1976 (Mosk. Inst. khim. mashinostr.).
4. MARTIROSIAN Z.A., On two contact problems for elastic circular cylinders of finite length. Izv. Akad. Nauk ArmSSR, Mekhanika, Vol. 31, No.5, 1978.
5. MELKONIAN A.P., On a mixed axisymmetric problem of the theory of elasticity for a cylinder of finite length. Izv. Akad. Nauk ArmSSR, Mekhanika, Vol. 24, No. 2, 1971.
6. BABLOIAN A.A. and MELKONIAN A.P., On an axisymmetric contact problem for a cylinder of finite length. Izv. Akad. Nauk ArmSSR, Mekhanika, Vol. 26, No.5, 1973.
7. BABLOIAN A.A. and MELKONIAN A.P., On two mixed axisymmetric problems of the theory of elasticity. Izv. Akad. Nauk ArmSSR, Mekhanika, Vol. 22, No.5, 1969.
8. ZLATIN A.N., Stretching of a cylinder containing periodically distributed disk-shaped cracks. Dokl. Akad. Nauk SSSR, Vol. 241, No.6, 1978.
9. BORODACHEV N.M., On imbedding of a stamp into the face of a semi-infinite elastic cylinder. Prikl. mekhan. Vol.3, No.9, 1967.
10. TIKHONOV A.N. and SAMARSKII A.G., Equations of Mathematical Physics. English translation, Pergamon Press, Book No. 10226, 1963.
11. GRADSHTEIN I.S., and RYZHIK I.N., Tables of Integrals, Sums, Series and Products. Moscow, "Nauka", 1971.
12. BABESHKO V.A. and VEKSLER V.E., wave excitation in a layer by a vibrating stamp. PMM Vol. 39, No. 5, 1975.
13. CHEBAKOV M.I., Method of homogeneous solutions in the mixed problem for a finite circular cylinder. PMM Vol.43, No.6, 1979.
14. VOROVICH I.I., ALEKSANDROV V.M. and BABESHKO V.A., Nonclassical Mixed Problems of the Theory of Elasticity. Moscow, "Nauka", 1974.
15. ALEKSANDROV V.M. and CHEBAKOV M.I., Mixed problems of the mechanics of continuous media associated with Hankel and Mehler-Fock integral transforms. PMM Vol. 36, No. 3, 1972.
16. CHEBAKOV M.I., On further development of the "method of large $\hat{n}$ " in the theory of mixed problems. PMM Vol. 4O, No. 3, 1976.
17. CHEBAKOV M.I., On the Reissner-Sagoci problem. Prikl. mekhan. Vol.9, No. 12, 1973.

[^0]:    *Prikl.Matem. Mekhan. , 44,No.5,923-933,1980

[^1]:    * Makhema V.K. Three-dimensional dynamic problems of steady-state oscillation of plates. Avtoref. Kand. dis. Rostov-on-Don, 1979.

